

Exercices

3.1) $\mathcal{L} = \frac{1}{2} \dot{\varphi}^2 - \frac{1}{2} (\vec{\nabla} \varphi)^2 - V(\varphi)$ avec $V(\varphi) = \frac{1}{2} m^2 \varphi^2$

$$\mathcal{L} = \frac{1}{2} \eta^{\mu\nu} (\partial_\mu \varphi) (\partial_\nu \varphi) - V(\varphi)$$

Euler-Lagrange: $\partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} - \frac{\partial \mathcal{L}}{\partial \varphi} = 0$

$$\frac{\partial \mathcal{L}}{\partial \varphi} = -m^2 \varphi$$

$$\left. \begin{aligned} \partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} &= \partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} - \partial_\mu \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} = \\ &= \partial_\mu (\partial_\mu \varphi) - \partial_\mu (\partial_\mu \varphi) = \\ &= \partial_\mu^2 \varphi - \Delta \varphi = \square \varphi \end{aligned} \right\} \Rightarrow \square \varphi + m^2 \varphi = 0$$

3.2) $T^{\mu\nu} = \frac{\partial \mathcal{L}}{\partial (\partial_\mu \varphi)} (\partial^\nu \varphi) - \eta^{\mu\nu} \mathcal{L}$

$$T^{00} = \frac{\partial \mathcal{L}}{\partial (\partial_0 \varphi)} (\partial^0 \varphi) - \mathcal{L} = \underbrace{\frac{\partial \mathcal{L}}{\partial \dot{\varphi}}}_{= \dot{\varphi} = \pi} \dot{\varphi} - \mathcal{L} = \pi \dot{\varphi} - \mathcal{L} = \mathcal{H}$$

$$3.3] \quad \varphi(x) = \int d\tilde{k} \left[a(\tilde{k}) e^{-ikx} + a^\dagger(\tilde{k}) e^{ikx} \right]$$

$$\square \varphi + m^2 \varphi = \partial_t^2 \varphi - (\vec{\nabla} \varphi)^2 + m^2 \varphi \stackrel{!}{=} 0$$

$$kx = k^0 x^0 - k^i x_i = k^0 \cdot t - k^i x_i \quad k^0 = \sqrt{\vec{k}^2 + m^2}$$

$$\partial_t \varphi = \int d\tilde{k} \left[a(\tilde{k}) e^{-ikx} (-ik^0) + a^\dagger(\tilde{k}) e^{ikx} (ik^0) \right]$$

$$\partial_t^2 \varphi = - \int d\tilde{k} \left[a(\tilde{k}) e^{-ikx} (k^0)^2 + a^\dagger(\tilde{k}) e^{ikx} (k^0)^2 \right]$$

$$\uparrow (k^0)^2 = \vec{k}^2 + m^2 \uparrow$$

$$\vec{\nabla} \varphi = \int d\tilde{k} \left[a(\tilde{k}) e^{-ikx} (i\vec{k}) + a^\dagger(\tilde{k}) e^{ikx} (-i\vec{k}) \right]$$

$$\vec{\nabla}^2 \varphi = - \int d\tilde{k} \left[a(\tilde{k}) e^{-ikx} \vec{k}^2 + a^\dagger(\tilde{k}) e^{ikx} \vec{k}^2 \right]$$

$$\Rightarrow \square \varphi + m^2 \varphi = -(\vec{k}^2 + m^2) \int d\tilde{k} [\dots] + \vec{k}^2 \int d\tilde{k} [\dots] + m^2 \int d\tilde{k} [\dots] = 0$$

$$\begin{aligned}
3.4) \quad [\varphi(x), \pi(y)] &= [\varphi(x), \dot{\varphi}(y)] = \\
&= \left[\int d\vec{k} (a(\vec{k}) e^{-ikx} + a^\dagger(\vec{k}) e^{ikx}), \int d\vec{p} (-i\omega_p a(\vec{p}) e^{-ipy} + i\omega_p a^\dagger(\vec{p}) e^{ipy}) \right] = \\
&= \int d\vec{k} \underbrace{\int d\vec{p}}_{\substack{= \frac{d\vec{p}}{(2\pi)^3 2\omega_p}}} \left(i\omega_p e^{-ikx} e^{ipy} \underbrace{[a(\vec{k}), a^\dagger(\vec{p})]}_{(2\pi)^3 2\omega_k \delta(\vec{k}-\vec{p})} - i\omega_p e^{ikx} e^{-ipy} \underbrace{[a^\dagger(\vec{k}), a(\vec{p})]}_{-(2\pi)^3 \omega_k \delta(\vec{k}-\vec{p})} \right) = \\
&= \int d\vec{k} \frac{i}{2} \int d\vec{p} \left(2\omega_k e^{-ikx} e^{ipy} \delta(\vec{k}-\vec{p}) + 2\omega_k e^{ikx} e^{-ipy} \delta(\vec{k}-\vec{p}) \right) = \\
&= \underbrace{\int d\vec{k}}_{\substack{= \frac{d\vec{k}}{(2\pi)^3 2\omega_k}}} \frac{i}{2} 2\omega_k \int d\vec{p} (e^{-ikx+ipy} + e^{ikx-ipy}) \delta(\vec{k}-\vec{p}) = \\
&= \frac{i}{2} \int \frac{d\vec{k}}{(2\pi)^3} (e^{-ik(x-y)} + e^{ik(x-y)}) \stackrel{k(x-y) = k^0(t-t) - \vec{k}(\vec{x}-\vec{y})}{=} \\
&= \frac{i}{2} \int \frac{d\vec{k}}{(2\pi)^3} (e^{i\vec{k}(\vec{y}-\vec{x})} + e^{i\vec{k}(\vec{x}-\vec{y})}) = \\
&= \frac{i}{2} (\delta(\vec{y}-\vec{x}) + \delta(\vec{x}-\vec{y})) = i\delta(\vec{x}-\vec{y})
\end{aligned}$$