

Exercices

$$\textcircled{1} \quad \mathcal{L} = \frac{1}{2}(\partial_r \phi)(\partial^r \phi) - \frac{\lambda}{4}(\phi^2 - v^2)^2 = \frac{1}{2}(\partial_r \vec{\varphi})(\partial^r \vec{\varphi}) - \frac{\lambda}{4}(\vec{\varphi}^2 - v^2)^2$$

$$\vec{\varphi} = \vec{\varphi}_0 + \vec{h} = \begin{pmatrix} v \\ 0 \\ h_2 \end{pmatrix} \rightarrow \vec{\varphi}^2 = \vec{\varphi}_0^2 + 2\vec{\varphi}_0 \cdot \vec{h} + \vec{h}^2 = v^2 + 2\vec{\varphi}_0 \cdot \vec{h} + \vec{h}^2$$

$$\partial_r \vec{\varphi} = \partial_r \vec{h}$$

$$\Rightarrow \mathcal{L} = \frac{1}{2}(\partial_r \vec{h})(\partial^r \vec{h}) - \frac{\lambda}{4}(2\vec{\varphi}_0 \cdot \vec{h} + \vec{h}^2) =$$

$$= \frac{1}{2}(\partial_r h_1)(\partial^r h_1) + \frac{1}{2}(\partial_r h_2)(\partial^r h_2) - \frac{\lambda}{4}(2v h_1 + h_1^2 + h_2^2)^2 =$$

$$= \frac{1}{2}(\partial_r h_1)(\partial^r h_1) + \frac{1}{2}(\partial_r h_2)(\partial^r h_2) - \lambda v h_1^2 - \lambda v h_1(h_1^2 + h_2^2) - \frac{\lambda}{4}(h_1^2 + h_2^2)^2$$

$$\textcircled{2} \quad V(\vec{\varphi}) = V(R) \quad \text{avec } R^2 = \vec{\varphi}^2 = \sum_i \varphi_i^2$$

$$\frac{\partial V}{\partial \varphi_i} = \frac{dV}{dR} \frac{\partial R}{\partial \varphi_i} = V'(R) \cdot \frac{\partial}{\partial \varphi_i} \sqrt{\sum_j \varphi_j^2} = V'(R) \cdot \frac{2\varphi_i}{2\sqrt{\sum_j \varphi_j^2}} = V'(R) \cdot \frac{\varphi_i}{R}$$

$$\frac{\partial^2 V}{\partial \varphi_i \partial \varphi_j} = \frac{\partial}{\partial \varphi_i} \left[V'(R) \cdot \frac{\varphi_j}{R} \right] = V''(R) \frac{\varphi_i}{R} \frac{\varphi_j}{R} + V'(R) \frac{\partial}{\partial \varphi_i} \left[\frac{\varphi_j}{R} \right] =$$

$$= V''(R) \frac{\varphi_i}{R} \frac{\varphi_j}{R} + V'(R) \cdot \frac{\delta_{ij}}{R} + V'(R) \underbrace{\varphi_i \frac{\partial}{\partial \varphi_i} \frac{1}{\sqrt{\sum_k \varphi_k^2}}}_{= -\frac{\varphi_i}{\sum_k \varphi_k^2}} =$$

$$= V''(R) \frac{\varphi_i \varphi_j}{R^2} + \frac{V'(R)}{R} \left[\delta_{ij} - \frac{\varphi_i \varphi_j}{R} \right]$$

$\textcircled{3}$ fait en cours.