

Tools and Monte-Carlos

for the

Old and New Physics

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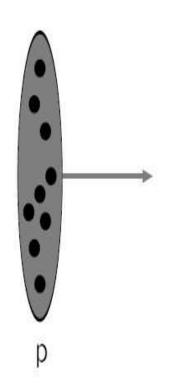


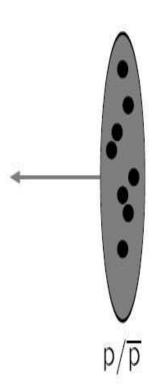
Nobel Dreams

Great Idea: A New Physics Model

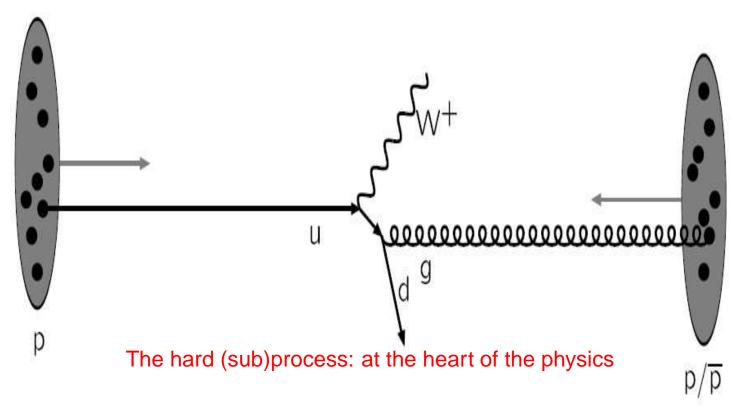
FINAL AIM

Nobel Prize if LHC validates!

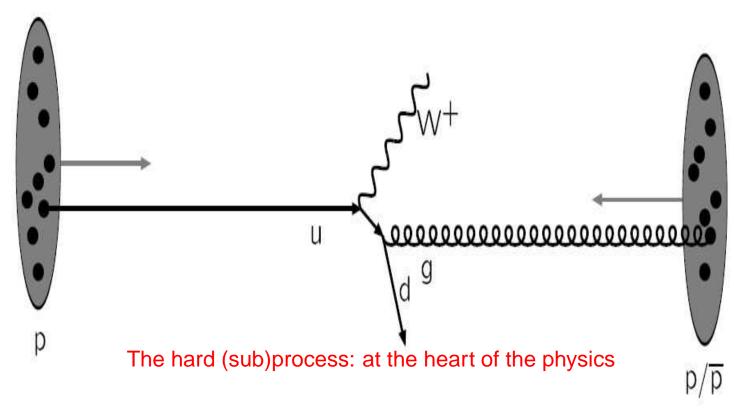




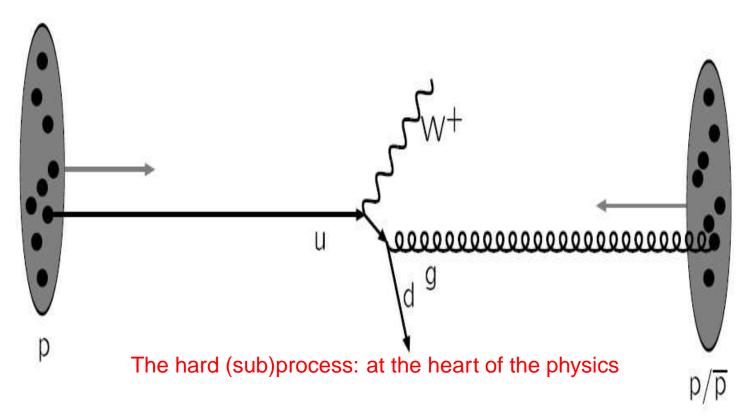
Incoming beams: partons densities



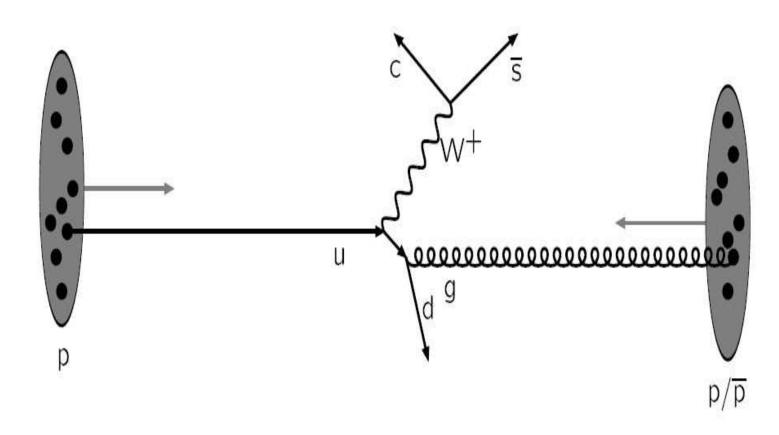
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- described by Matrix Elements (ME)
 This does not mean that it is very well calculated

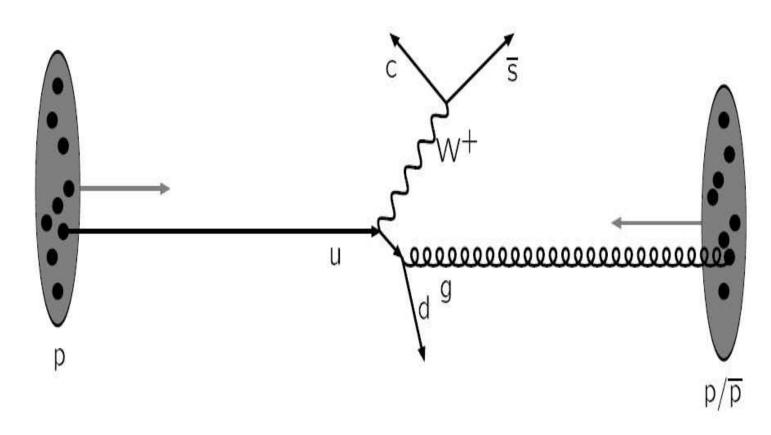


- Hard process is well understood and well described: relies on a firm perturbative framework.
- described by Matrix Elements (ME)
 This does not mean that it is very well calculated
- issue of higher order (NLO), most calculations only LO say



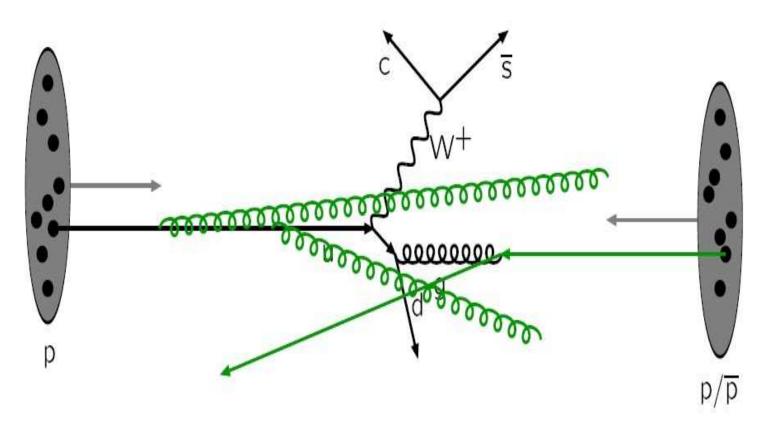
Decays of resonances: correlated with hard process

lacksquare Approximation: W on-shell

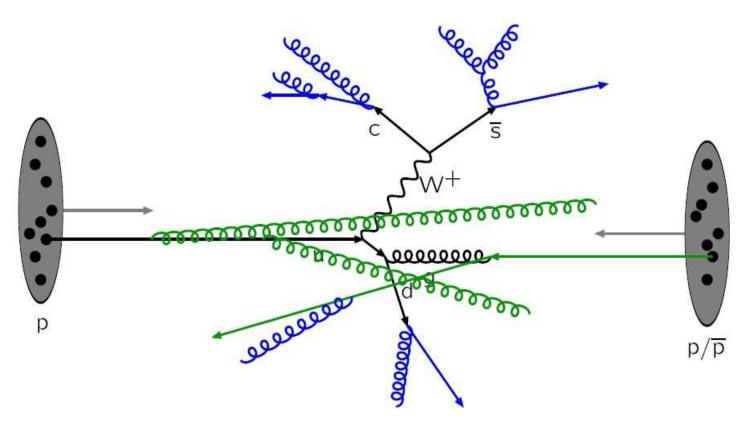


Decays of resonances: correlated with hard process

- lacksquare Approximation: W on-shell
- Spin effect in decays?

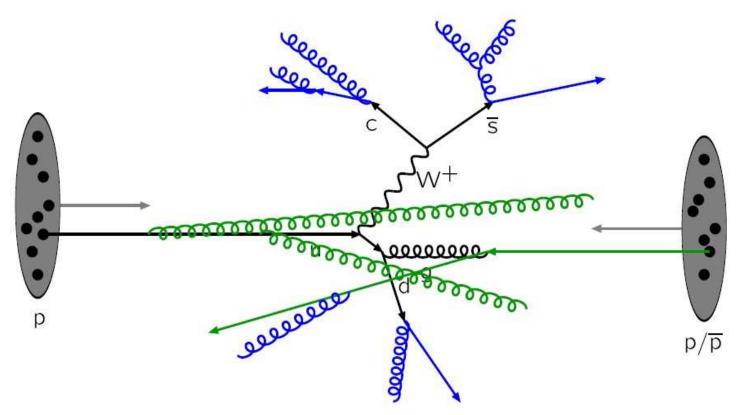


ISR: Initial State Radiation
Space-like parton showers (PS)



FSR: Final State Radiation

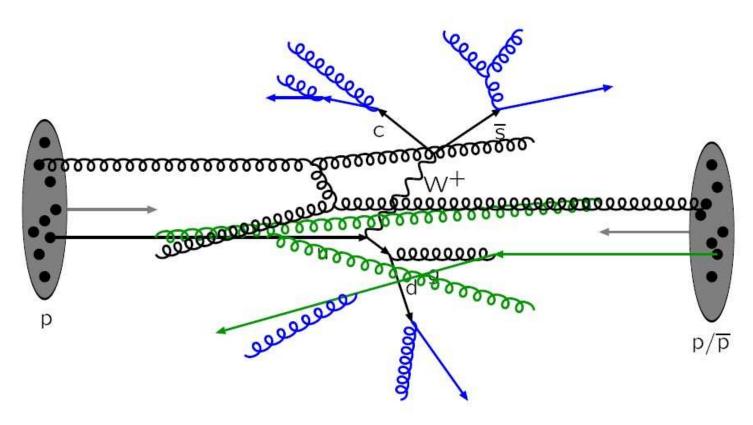
time-like parton showers (PS)



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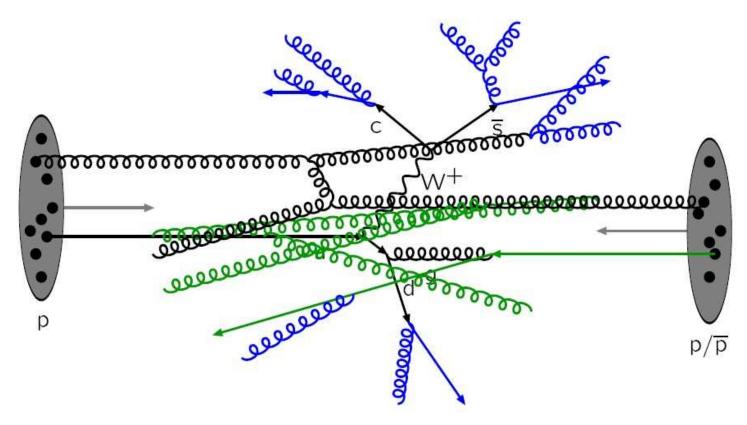
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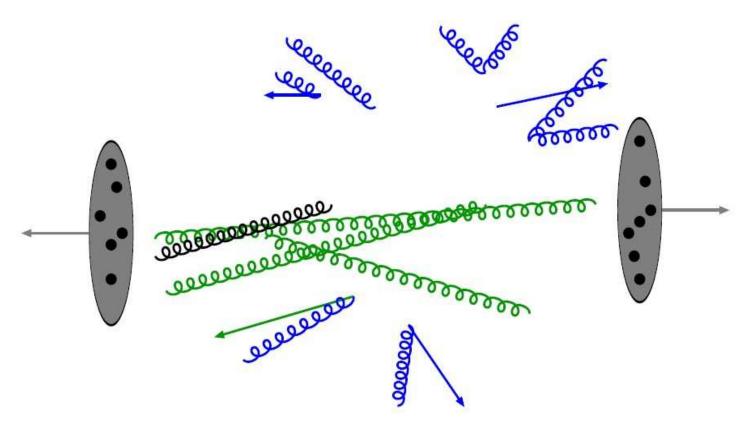
Multiple parton-parton interactions (MPI)

The muck



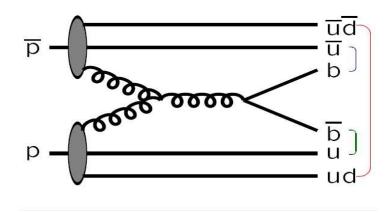
MPI with ISR and FSR!

The muck

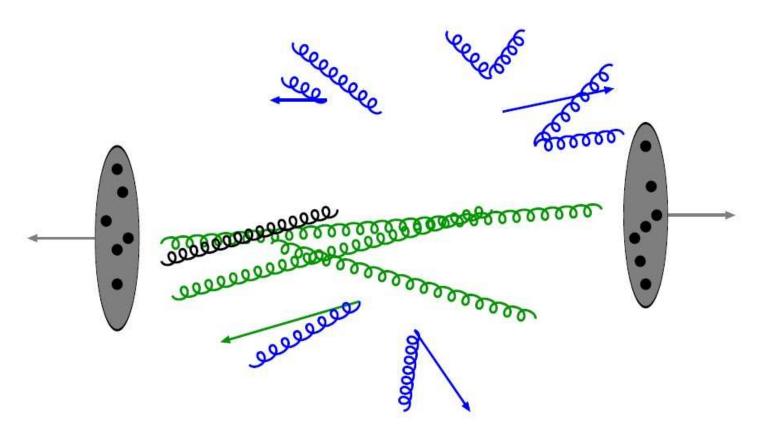


Beam remnants and other outgoing partons!

The muck

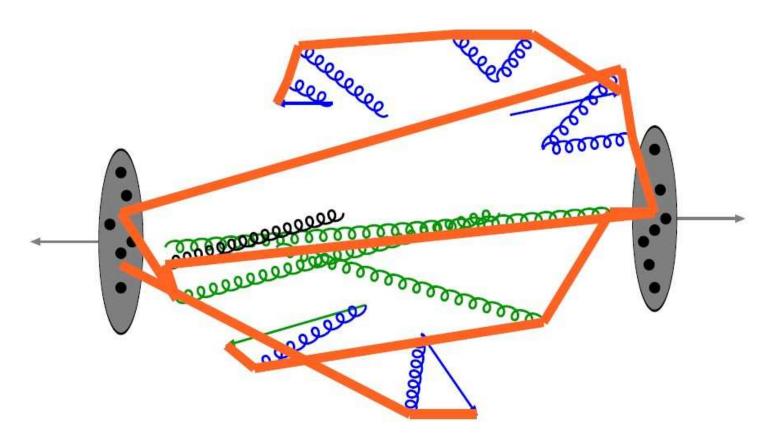


Beam remnants: coloured remains of the proton not taking part in the hard process, but they are colour connected to the hard process.

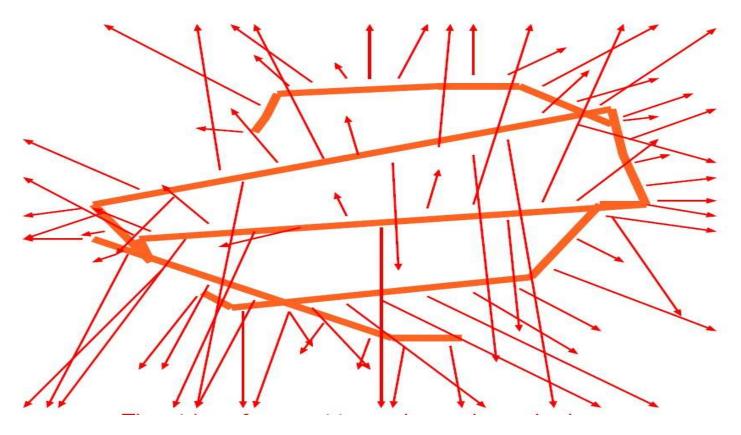


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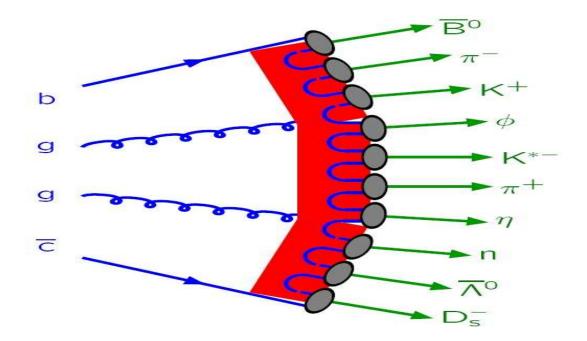
The muck: UE is not understood. It is modelled through some data that do not give strong constraints and hence extrapolation can be doubted.



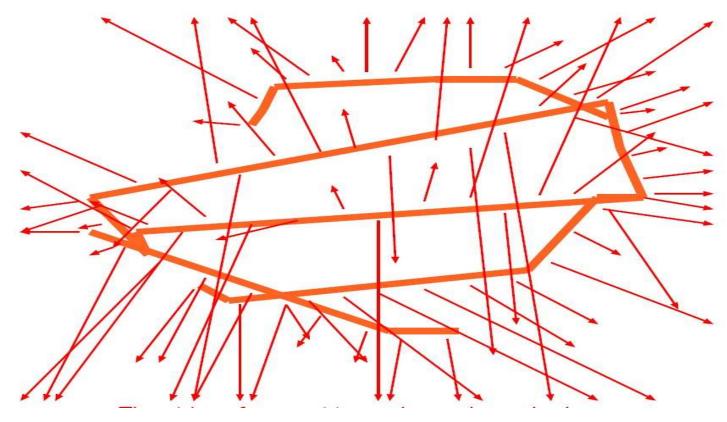
Everything is connected by colour confinement (here strings)



The strings fragments to produce hadrons

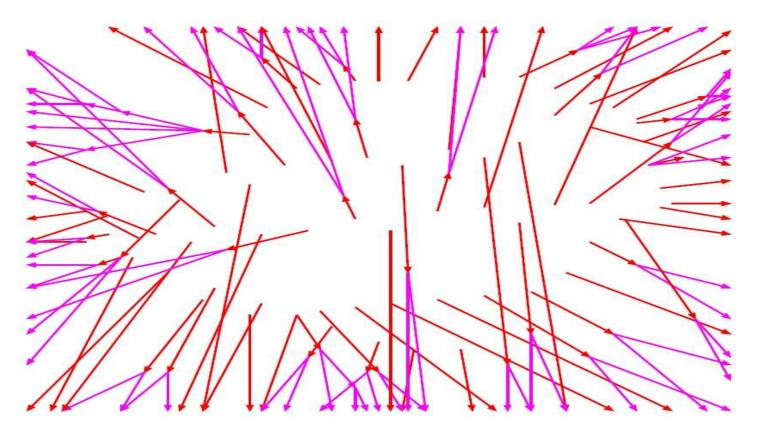


Hadronisation: Clusters to produce hadrons (Cluster Model)

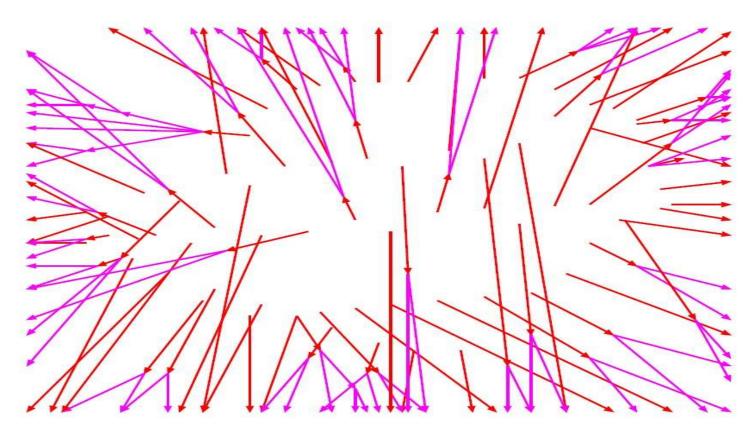


The strings fragments to produce hadrons (strings model)

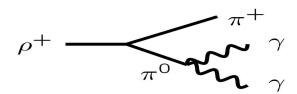
Hadronisation is not really calculated from first principles, however it is modelled through various data and hence it is considered reliable

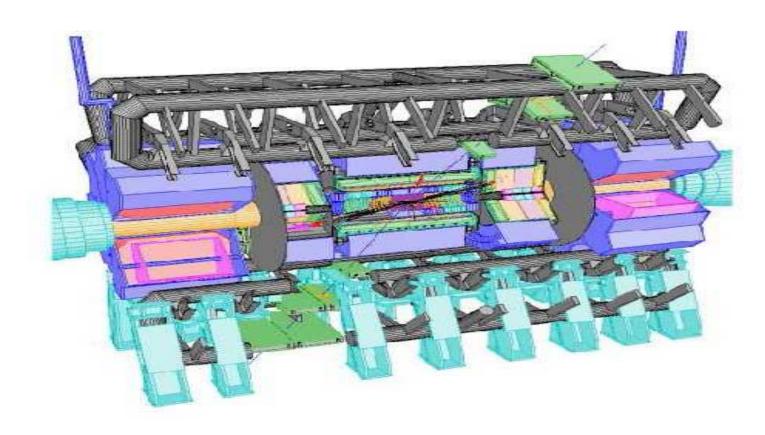


Hadrons decay



Hadrons decay





These are the particles that hit the detector

Parts of a MC EG

- Parton Shower is well understood, perturbation theory with a few approximations
- Hadronisation is not really calculated from first principles, however it is modelled through various data and hence it is considered reliable
- UE is not understood. It is modelled through some data that do not give strong constraints and hence extrapolation can be doubted.(minimum bias??)
- Important to have a "clear" picture of the physical situation

MC is probabilistic, divide and conquer

generate events with as much details as possible:

```
W will decay. To 	au?, 	au will decay, there is no quark, only hadrons,... production comes with non negligible radiation
```

- $m{ ilde{ heta}}_{ ext{final state}} = \sigma_{ ext{hard process}} \; \mathcal{P}_{ ext{tot}}$
- lacksquare Divide and Conquer : each \mathcal{P}_i handled in turn
- an event with n particles involve about 10n random choices (flavour, mass, momentum, spin,...). At the LHC expect about 100 charged and 200 neutral particles, thus totalling a few thousand choices

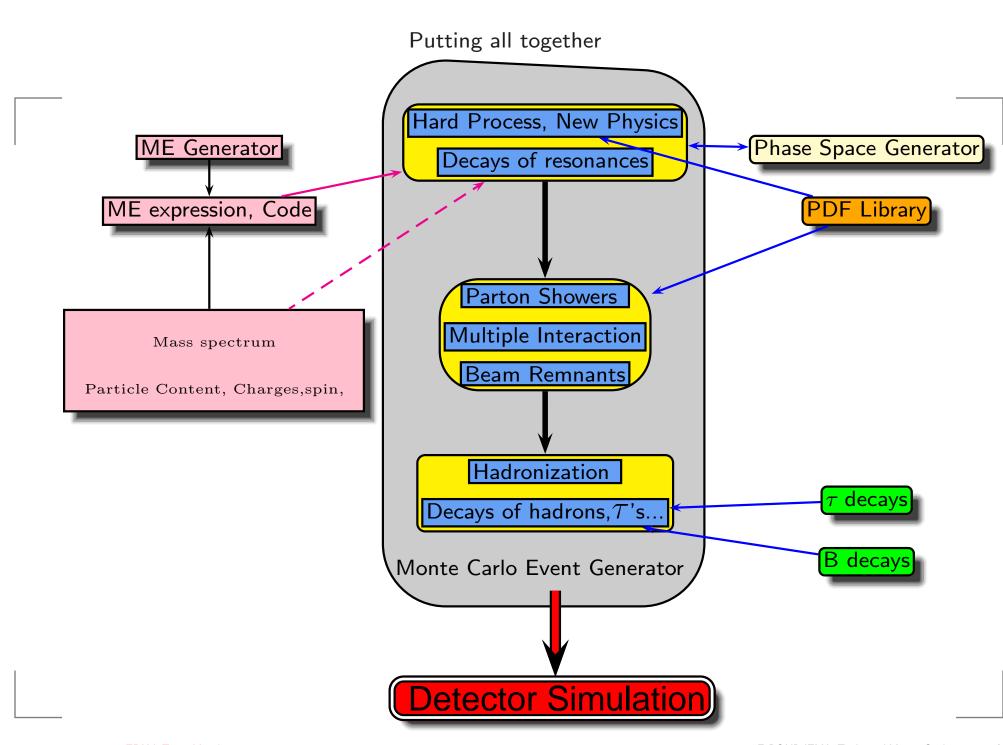
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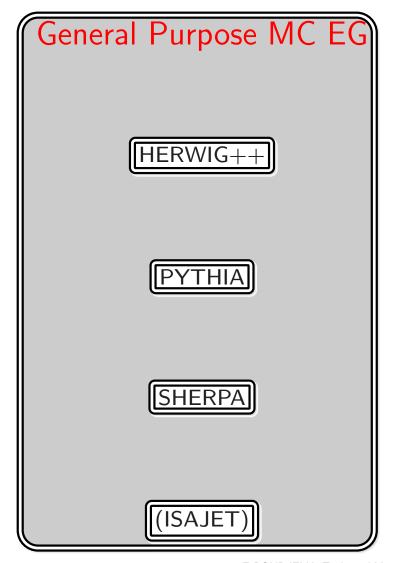
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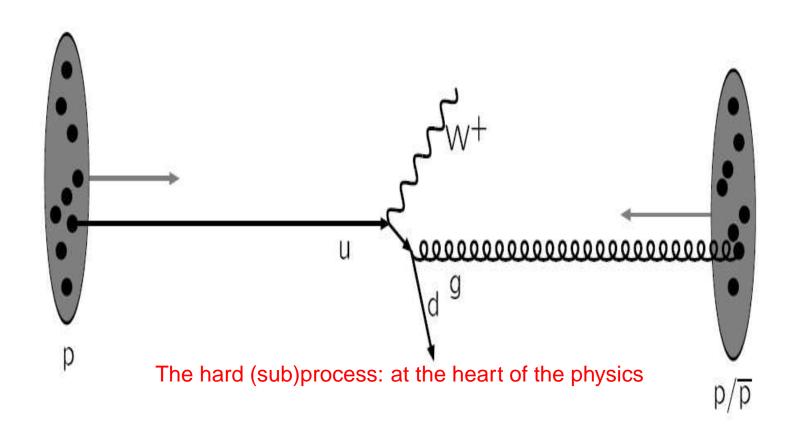
Divide and Conquer: each \mathcal{P}_i handled in turn \rightarrow Modular Structure



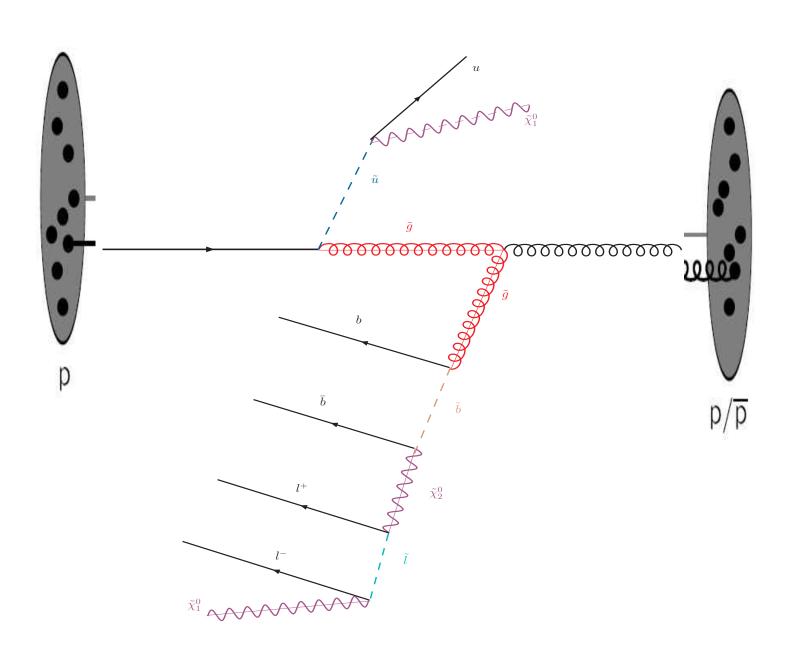




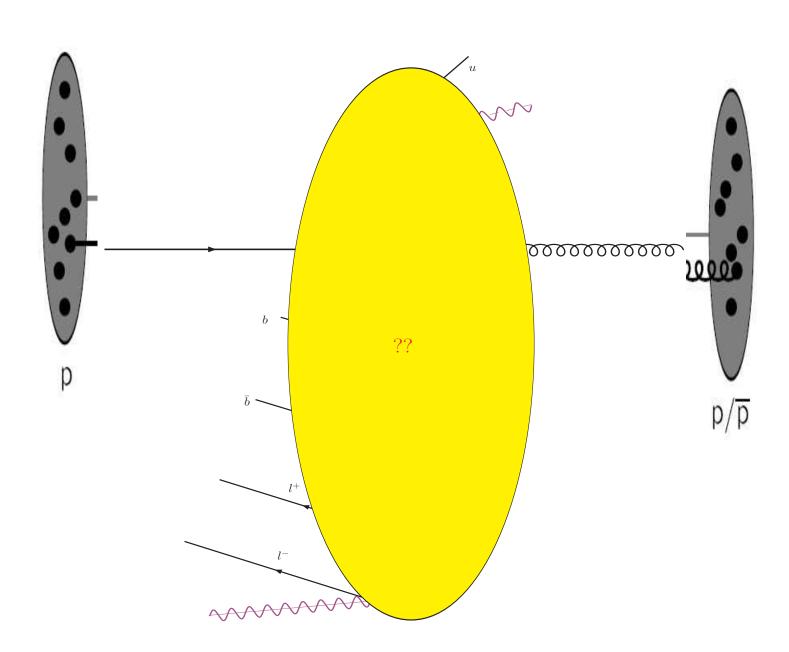
Integration: PDF and Cross sections



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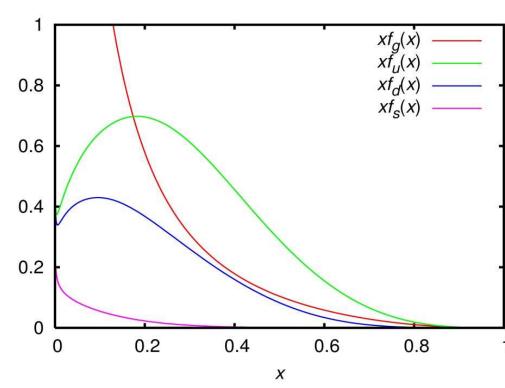
Integration: PDF and Cross sections



Factorisation and Parton Distribution Functions

$$\sigma_{pp\to X} = \sum_{a,b=q,\bar{q},g} \int dx_1 dx_2 f_a(x_1,\mu^2) f_b(x_2,\mu^2) \hat{\sigma}_{ab\to X}(\hat{s},\mu^2)$$

 $f_i(x,\mu^2)$ is the Parton Distributions Function μ^2 is the factorisation scale ! Many libraries exist (CTEQ, MRSx) reliable in the range $10^{-3} < x < 0.8 \ (2 {\rm GeV})^2 < \mu^2 < (1 TeV)^2$

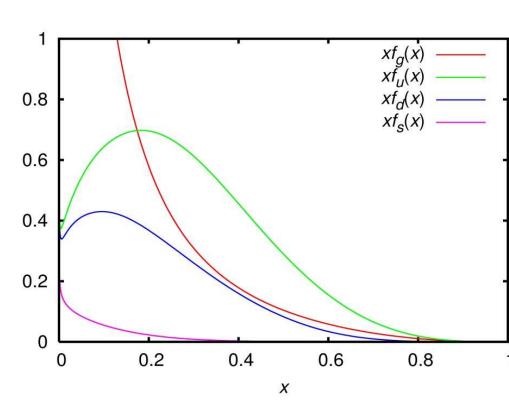


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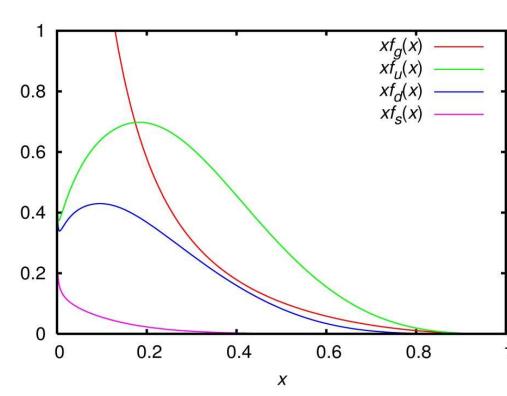
Phase Space

$$\hat{\sigma}_{ab\to X} = \frac{1}{2\hat{s}} \sum_{spin...} \int_{\Phi_N} |\mathcal{M}|^2 d\Phi_N$$

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Phase Space

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Monte-Carlo and Integration

At the heart of the ME is the hard process, that is where the physics lies and that is what gives the probability of a particular event For the hard process

- lacksquare amplitude $\mathcal{M} \longrightarrow |\mathcal{M}|^2$
- $N_{\rm evt,cuts} \propto \int d\sigma = \int |\mathcal{M}|^2 d\Phi(n)$
- Integration over a phase space with of large number n of dimensions, each particle $\rightarrow 3$ variables (momenta)
- $ightharpoonup Dim[d\Phi(n)] \sim 3n$

$$d\Phi(n) = \left(\prod_{i} n \frac{d^2 p_i}{(2\pi)^3 (2E_i)}\right) (2\pi)^4 \delta\left(P_{in} - \sum_{i}^{n} p_i\right)$$

Monte-Carlo Definition

- MC is a numerical method for calculating/estimating an integral based on a random evaluation of the integrand
- Particularly useful because one deals with a large number of (integration) variables (momenta of particles)
- Limits of integration (cuts) are often complicated
- Integrand is a convolution of different functions

One dimension, example

$$I = \int_{x_1}^{x_2} f(x)dx = (x_2 - x_1) < f(x) >$$
 (usually $x_1 = 0, x_2 = 1$)

The average can be calculated by selecting N values $randomly x_i, i = 1, \cdots N$ from uniform distribution, calculate $f(x_i)$

$$I = I_N = \frac{1}{N}(x_2 - x_1) \sum_{i=1}^{i=N} f(x_i) = \frac{1}{N} \sum_{i=1}^{i=N} W(x_i)$$
 $W(x_i) =$ weight

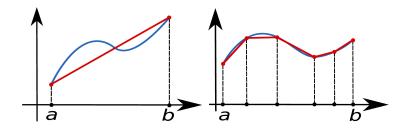
- Sum is invariant under reordering (randomize)
- lacksquare Obviously approximation better if number of points N is larger
- Error given by the Central Limit Theorem

$$I \simeq I_N \pm \sqrt{\frac{V_N}{N}} = I_N \pm \sqrt{\frac{\langle f^2 \rangle - \langle f \rangle^2}{N}}$$

 \blacksquare MC converges as $1/\sqrt{N}$

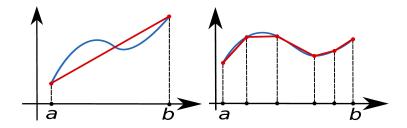
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- compare to trapezium rule convergence $\propto 1/N^2$ (if derivative exists)

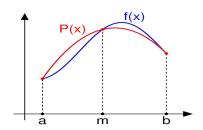


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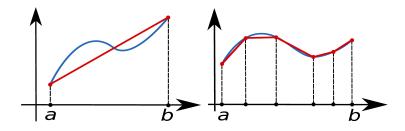


Simpson (quadratic interpolation) $\propto 1/N^4$ (if derivative exists)

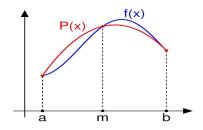


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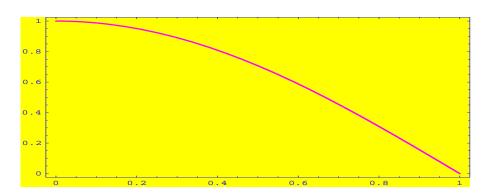
but this is only in one dimension!

- Convergence may seem slow $\sqrt{1/N}$, but it can be estimated easily
- MC error does not depend on # of dimensions, d, $\propto 1/\sqrt{N}$ Trapeze $\propto \to 1/N^{2/d}$ Simpson $\propto \to 1/N^{4/d}$
- ${\color{red} \bullet}$ in MC one can improve convergence by minimising V_N while keeping the same number of points N
- Importance Sampling: non uniform sampling more efficient
- Convergence improved by putting more samples in regions where function is largest (where variance is largest)
- ullet Hint: observe that if f(x)=cste then $V_N=0$ \to make f as a close to a constant as possible!

$$I \simeq I_N \pm \sqrt{\frac{V_N}{N}} = I_N \pm \sqrt{\frac{\langle f^2 \rangle - \langle f \rangle^2}{N}}$$

Example: Importance Sampling

Take
$$f(x) = cos\pi x/2$$
 then $I=2/\pi=0.637$ MC, $I_N=0.637\pm \frac{0.308}{\sqrt{N}}$ (0.308 = $\sqrt{V_N}=\sqrt{1/2-(2/\pi)^2}$)

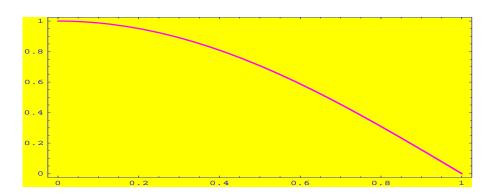


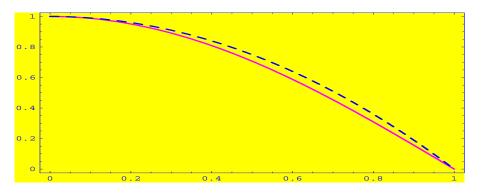
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$$I = \int_0^1 dx (1 - x^2) \frac{\cos \pi x/2}{1 - x^2}$$
$$= \int_{y_1}^{y_2} dy \frac{\cos \pi x[y]/2}{1 - x[y]^2}$$

MC,
$$I_N = 0.637 \pm 0.031/\sqrt{N}$$

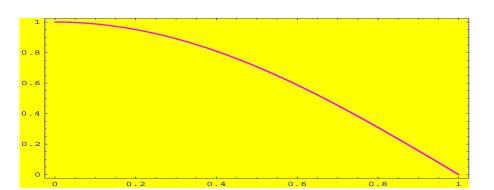


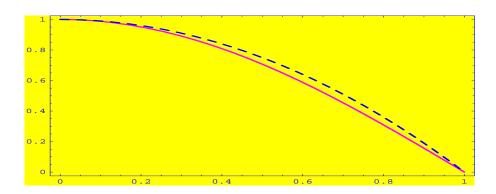


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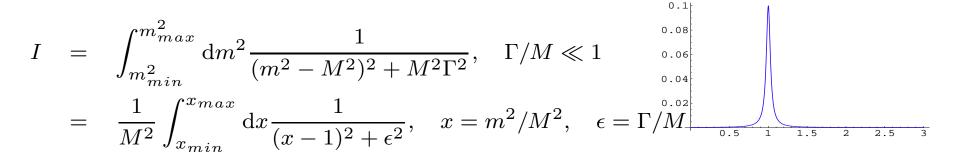
- **●** For the same accuracy $N \rightarrow N/100$ events
- We have in fact made a change of variables
- Note however that change of variables may be not so trivial and requires that one knows the function, here is relatively ok

$$y = x - x^3/3!$$

in HEP many sharp peaks from resonances, apart from peaks due to forward scattering,...

$$I = \int_{m_{min}^2}^{m_{max}^2} dm^2 \frac{1}{(m^2 - M^2)^2 + M^2 \Gamma^2}, \quad \Gamma/M \ll 1$$
$$= \frac{1}{M^2} \int_{x_{min}}^{x_{max}} dx \frac{1}{(x - 1)^2 + \epsilon^2}, \quad x = m^2/M^2, \quad \epsilon = \Gamma/M$$

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change of variable $x = \varepsilon \tan \theta + 1, dx = \varepsilon (1 + \tan^2 \theta) dt$

$$I = \frac{1}{M\Gamma} \int_{\theta_{min}}^{\theta_{max}} d\theta$$

The peak has been smoothed out completely.

Flat distribution, the error has been reduced to 0

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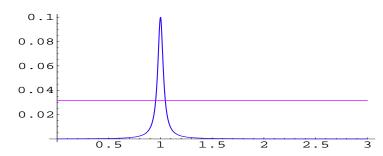
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Non-uniform, importance sampling

Unfortunately we can not always do the Jacobian trick efficiently, we do not always know $f(\boldsymbol{x})$

However, as we have seen, finding a simple function, p(x), that approximate f(x) reduces the error drastically (up to normalisation) take

$$p(x), \int_{x_1}^{x_2} p(x) = 1, \qquad \to I \qquad = \qquad \int_{x_1}^{x_2} dx p(x) \frac{f(x)}{p(x)}$$

$$I \qquad = \qquad \left\langle \frac{f}{p} \right\rangle \pm \frac{1}{\sqrt{N}} \sqrt{\left\langle \frac{f^2}{p^2} \right\rangle - \left\langle \frac{f}{p} \right\rangle^2}$$

Sample according to p(x) and make f/p as small as possible.

VEGAS (BASES) Importance+Stratified Sampling

Unfortunately we usually do not know much about f(x)

But as we sample we can know more, reconstruct p(x) piecemeal, with step function

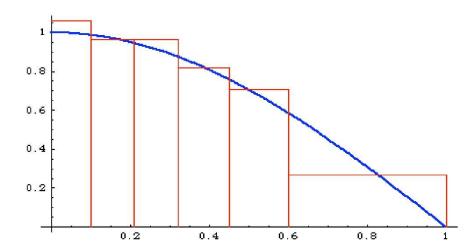
$$p(x) = \frac{1}{N_b} \Delta x_i \text{ for } x_i - \Delta x_i \le x \le x_i$$

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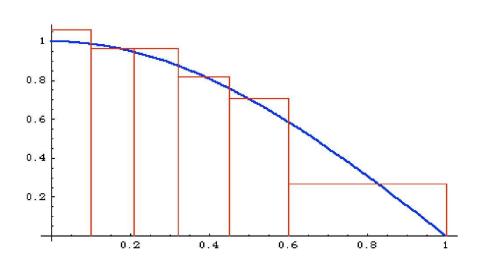


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- Improve the fit by generating more points where f(x) is large, *i.e* where the variance is large
- Adjust the bin size so that each bin has the same area

Iterative algorithm: VEGAS

■ The approach can be directly generalised to d dimensions if one can write the factorised from $p(\vec{x}) = p(x) \times p(y) \times \cdots$

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- This assumes that we have the correct grid: the peaks are localised and are aligned along the axes!

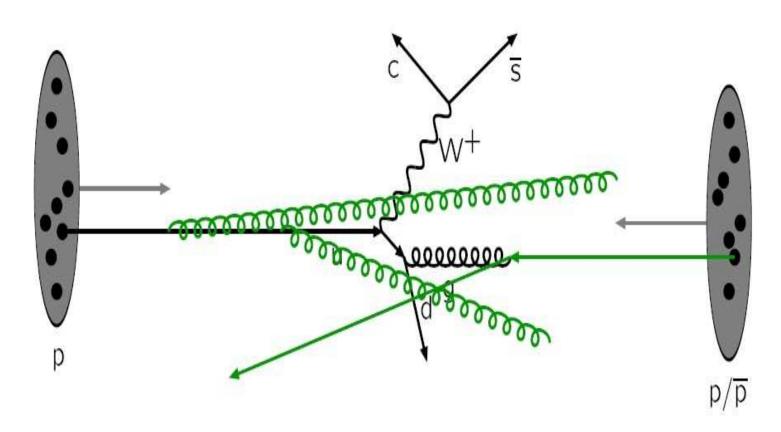
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- this means 2^n possible kinematical invariants
- A scattering amplitude may have many peaks each aligned on a different invariant

Remember the Movie: The structure of an event, ISR and FSR

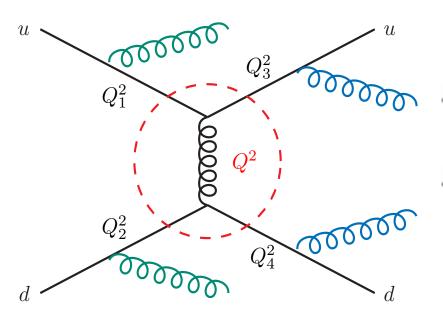


ISR: Initial State Radiation

Parton Shower Approach

 $\mathcal{P}_{ ext{ISR}/ ext{FSR}}$ Accelerated charged particles radiate

$$2 \rightarrow n = (2 \rightarrow 2)_{\mathrm{On\ Shell}}$$
 + ISR + FSR

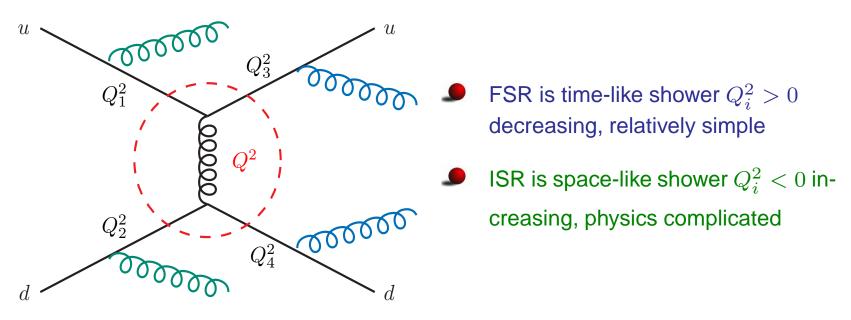


- FSR is time-like shower $Q_i^2 > 0$ decreasing, relatively simple
 - ISR is space-like shower $Q_i^2 < 0$ increasing, physics complicated

Parton Shower Approach

 $\mathcal{P}_{ ext{ISR}/ ext{FSR}}$ Accelerated charged particles radiate

$$2 \rightarrow n = (2 \rightarrow 2)_{\text{On Shell}} + \text{ISR} + \text{FSR}$$

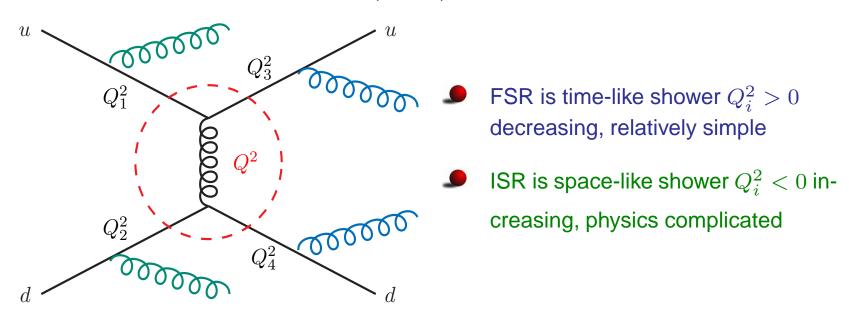


- Shower is viewed as a probabilistic process which occurs with unit probability
- The (total) cross section is not affected but indirectly it is since the event shape is changed
- Obviously it is an approximation to the full process

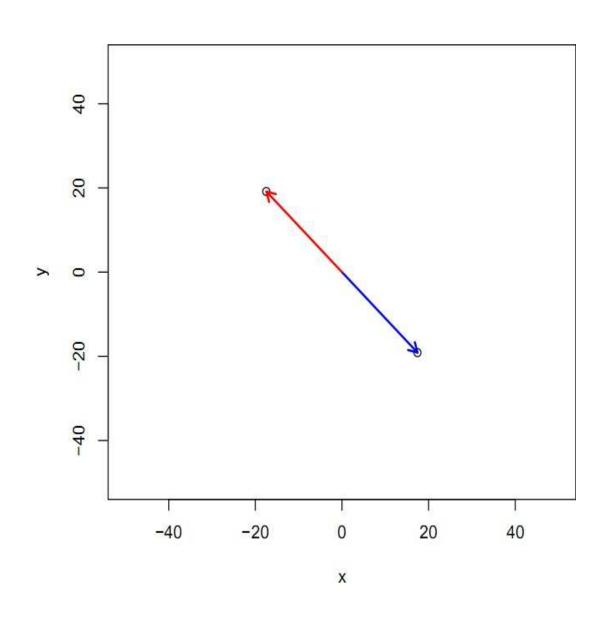
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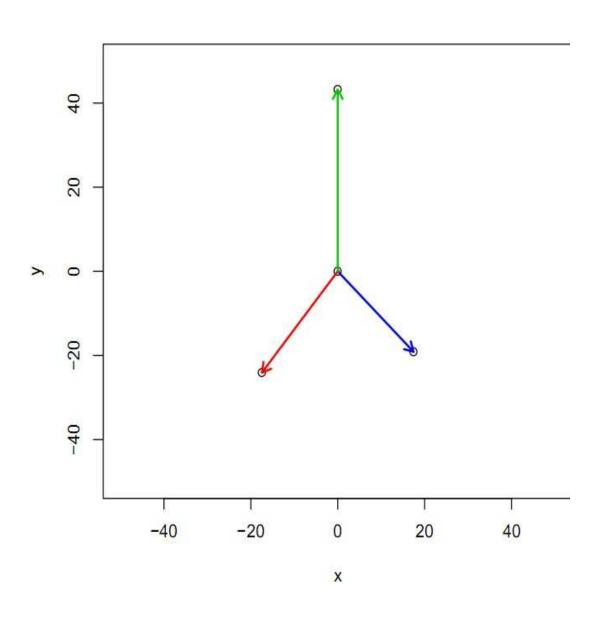
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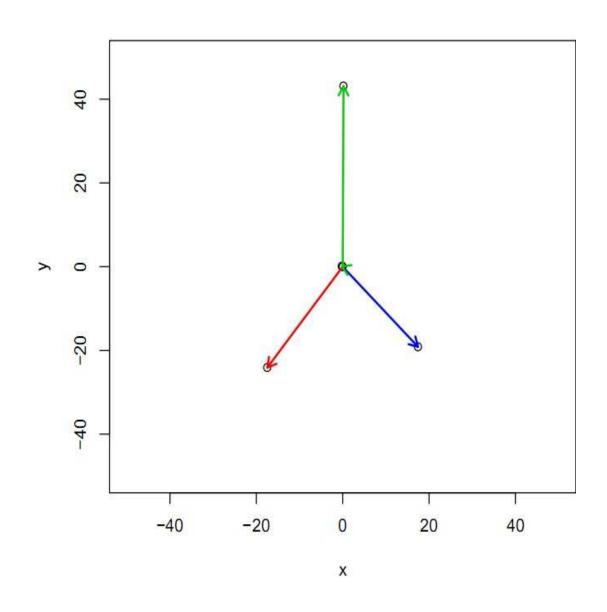
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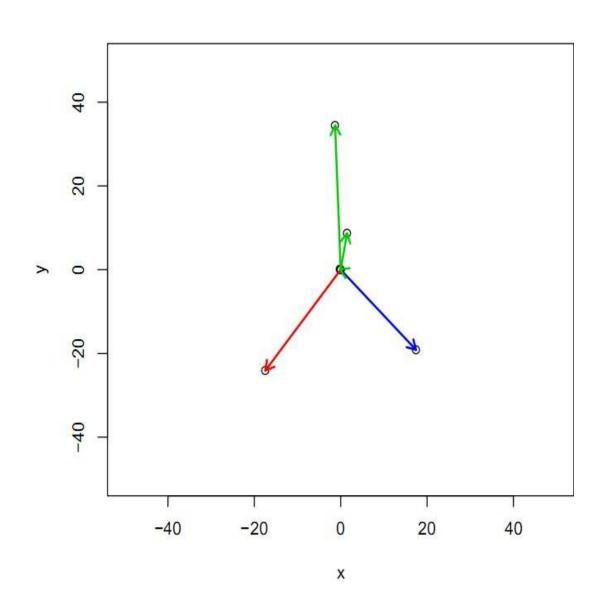


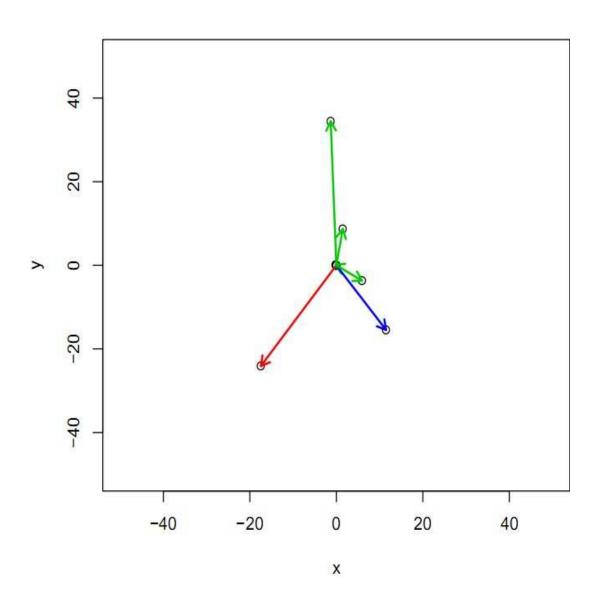
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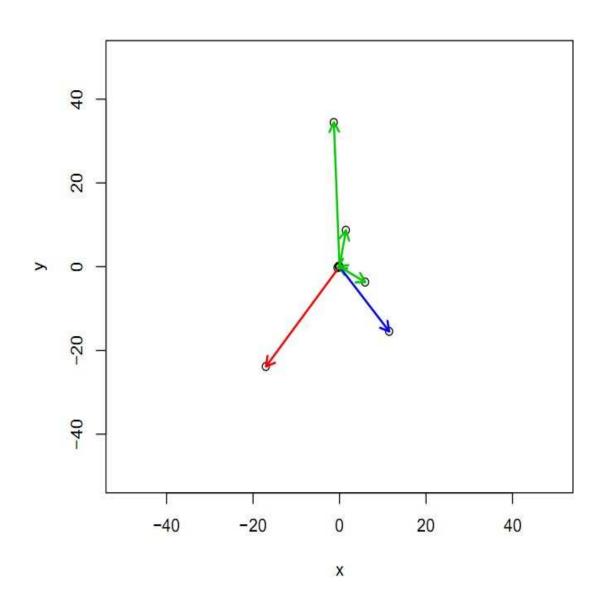


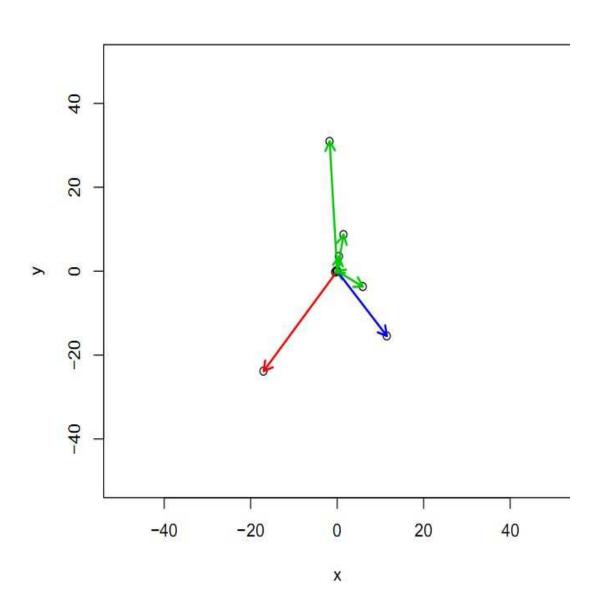


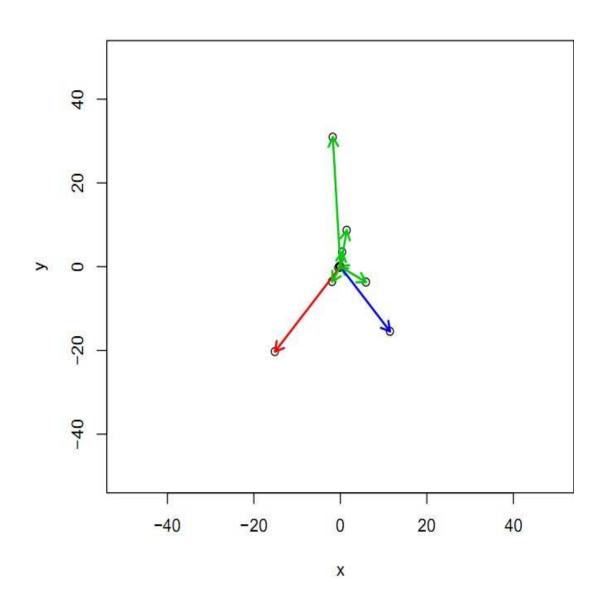


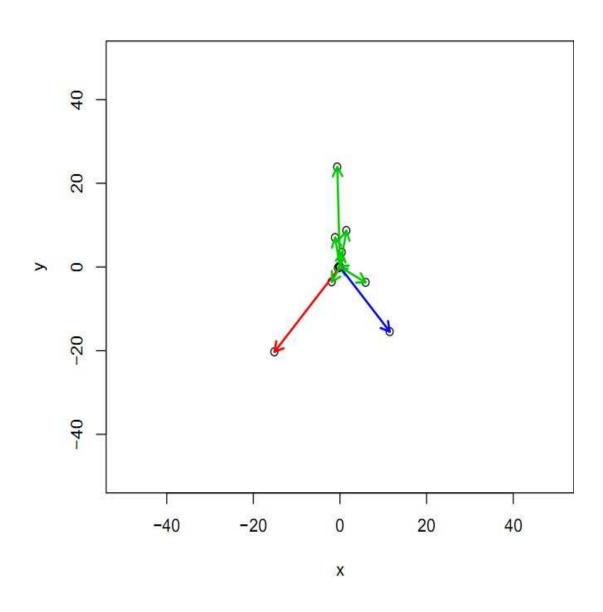


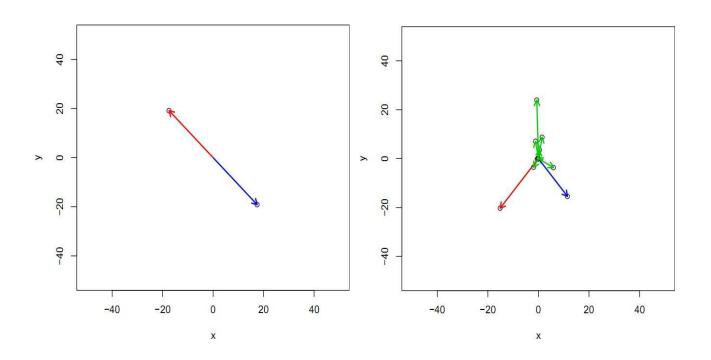




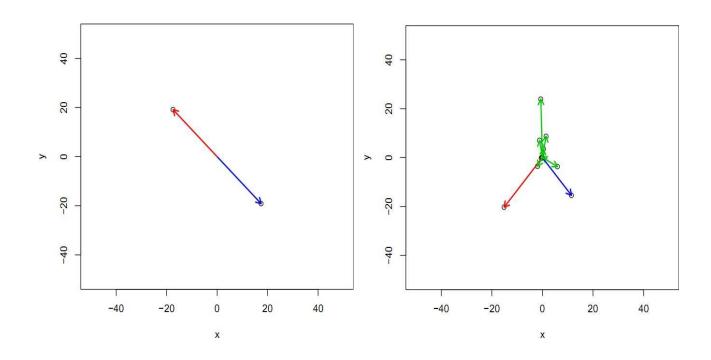




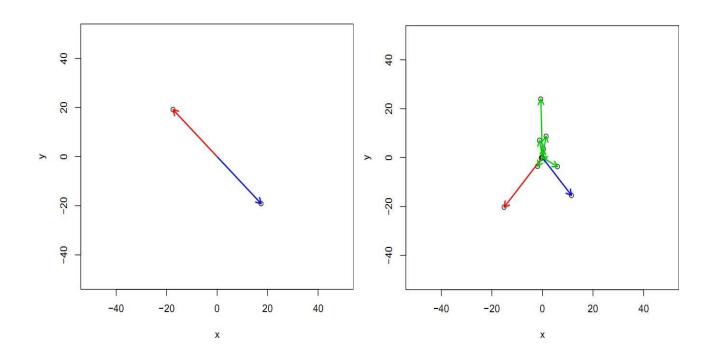




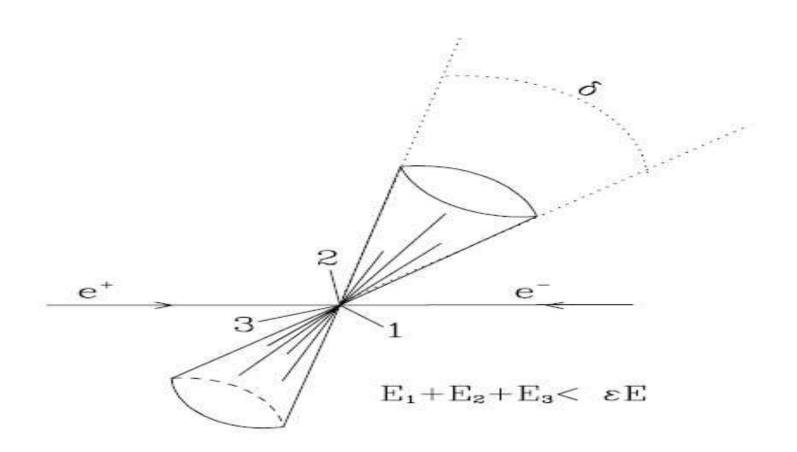
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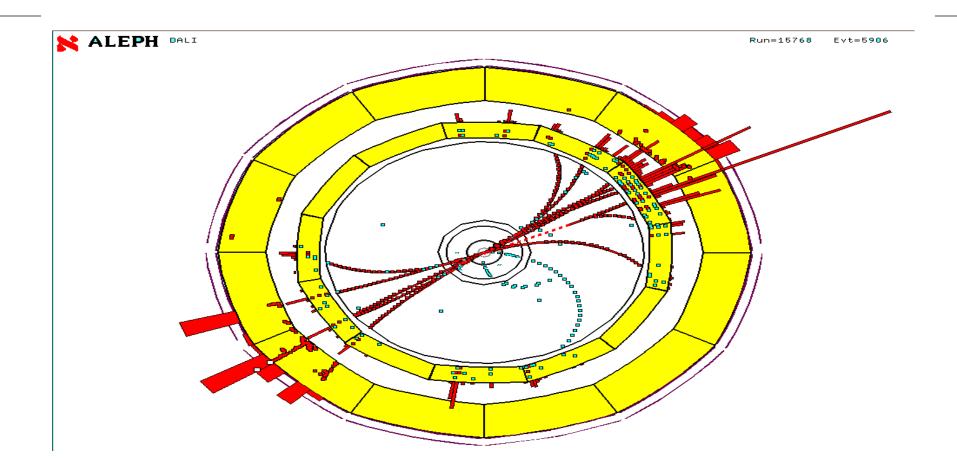
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- These are events shape that can not be described by fixed order pert. calculations



- The topology generated by the PS can be quite complicated
- These are events shape that can not be described by fixed order pert. calculations
- Total cross section still given by hard scattering (usually LO), experiments usually normalise to data



Jets 1.



Jets 2.

