

Classification of Non-Affine Non-Hecke Dynamical R-Matrices

The G-N-F Dynamical Quantum Yang-Baxter Equation

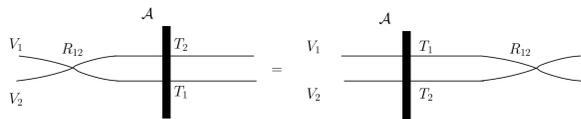
The Gervais-Neveu-Felder dynamical quantum Yang-Baxter equation (G-N-F DQYBE) reads:

$$R_{12}(\lambda + 2\gamma h_3)R_{13}(\lambda)R_{23}(\lambda + 2\gamma h_1) = R_{23}(\lambda)R_{13}(\lambda + 2\gamma h_2)R_{12}(\lambda)$$

This G-N-F DQYBE may be obtained by different approaches:

- Originally formulated by Gervais and Neveu in the context of quantum Liouville theory.
- Built by Felder as a quantization of the so-called modified dynamical classical Yang-Baxter equation. This classical equation itself can be seen as a compatibility condition of Knizhnik-Zamolodchikov-Bernard equations and also arose when considering the Lax formulation of the Calogero-Moser and Ruijsenaar-Schneider model, and particularly its r -matrix.
- Seen as a consistency condition for the dynamical quantum group relation (DQGR): $R_{12}(\lambda + \gamma h_q)T_1(\lambda - \gamma h_2)T_2(\lambda + \gamma h_1) = T_2(\lambda - \gamma h_1)T_1(\lambda + \gamma h_2)R_{12}(\lambda - \gamma h_q)$

The DQGR in short:



T ($T \in \text{End}(V \otimes \mathcal{A})$) is the so-called transfer-matrix and R ($R \in \text{End}(V \otimes V)$) the R -matrix seen as a matrix of structure coefficients for the quadratic exchange relations of \mathcal{A} , the considered (dynamical) quantum algebra.

Here, the quantum group relation is dynamical since both R and T depend on a finite family $(\lambda_i)_{i \in \mathbb{N}_n^*}$ of c -number complex “dynamical” parameters, the term “dynamical” comes from the identification of these parameters in the classical limit with the position variables in the context of classical Calogero-Moser or Ruijsenaar-Schneider models.

These “dynamical” parameters λ_i 's can be understood as coordinates on the dual algebra \mathfrak{h}^* of a n -dimensional complex Lie algebra \mathfrak{h} . We shall suppose here that:

- \mathfrak{h} is abelian
 - the finite vector space V is a n -dimensional diagonalizable module of \mathfrak{h}
- That is: V is a n -dimensional vector space with the weight decomposition $V = \bigoplus_{\mu \in \mathfrak{h}^*} V[\mu]$, where the weight spaces $V[\mu]$ are irreducible modules of \mathfrak{h} , hence are one-dimensional.

The operator R is therefore represented by an $n^2 \times n^2$ matrix. The shift of λ (vector of \mathfrak{h}^*) by some γh_q is defined for any $v_1, v_2 \in V^2$ as follows: $T_1(\lambda + \gamma h_2)v_1 \otimes v_2 = T_1(\lambda + \gamma \mu_2)v_1 \otimes v_2$, where μ_2 is the weight of v_2 .

If the R -matrix obeys the so-called zero-weight condition under adjoint action of any element $h \in \mathfrak{h}$: $[h_1 + h_2, R_{12}] = 0$, the associativity condition on the DQGR implies the G-N-F dynamical quantum Yang-Baxter algebra for R .

Hecke and Weak Hecke conditions

Hecke condition:

The Hecke condition restricts the eigenvalues of the permuted R -matrix $\check{R} = PR$ (P being the permutation operator of vector spaces $V \otimes \mathbb{I}_d$ and $\mathbb{I}_d \otimes V$) to take only:

- one value ρ on each one-dimensional vector space $V_{ii} = \mathbb{C}v_i \otimes v_i$, for any indice $i \in \mathbb{N}_n^*$,
- and the two distinct values ρ and $-\kappa$ on each two-dimensional vector space $V_{ij} = \mathbb{C}v_i \otimes v_j \oplus \mathbb{C}v_j \otimes v_i$, for any pair of distinct indices $(i, j) \in (\mathbb{N}_n^*)^2$, $(v_i)_{i \in \mathbb{N}_n^*}$ being a basis of V .

Early examples of non-affine solutions have been brought to light under the hypothesis that R obeys Hecke condition.

The classification of Hecke type non-affine solutions has been succeeded for a long time starting with the pioneering works of Etingof.

weak Hecke condition:

The less constraining “weak Hecke” condition only assumes the existence of two c -numbers ρ and κ , with $\rho \neq -\kappa$, such that $(\check{R} - \rho)(\check{R} + \kappa) = 0$.

The weak Hecke condition can be understood as a quantization of the skew-symmetry condition on the classical dynamical r -matrices $r_{12} = -r_{21}$.

Direct connection between classical and quantum dynamical Yang Baxter equation only holds if the r -matrix is skew-symmetric. Dropping the weak Hecke condition may thus modify the understanding of DQYBE as a deformation of a classical structure, but keeps the characteristic quantum structures: coproduct, coactions, fusion of T -matrices and quantum trace (yielding commuting Hamiltonians).

The classification of non-affine R -matrices, solutions of DQYBE, without (weak) Hecke condition was done by Ju, Luo, Wang and Wu in the case of $\mathcal{G}l_2(\mathbb{C})$ and for trigonometric behavior only.

Setting the problem to solve

We propose a complete classification of invertible R -matrices satisfying the zero weight condition solving the DQYBE for $V = \mathbb{C}^n$.

We choose \mathfrak{h} to be the Cartan algebra of $\mathcal{G}l_n(\mathbb{C})$.

This classification is proposed within the following framework:

- We consider non-spectral parameter dependent R -matrices (called “constant” in the literature on quantum R -matrices but not here to avoid ambiguities with the dependency in the “dynamical” parameters). This implies a priori no elliptic dependence of the solutions in the dynamical variables, at least in the Hecke case.
- We assume the matrix R to be invertible. Non-invertible R -matrices are expected to correspond to an inadequate choice of auxiliary space V (e.g. reducible). It precludes even the proof of commutation of the traces of monodromy matrices, at least by using the dynamical quantum group structure, hence such R -matrices present a lesser interest.
- We assume that the elements of the matrix R have sufficient regularity properties as functions of their dynamical variables, so that we are able to solve any equation of the form $A(\lambda)B(\lambda) = 0$ as $A(\lambda) = 0$ or $B(\lambda) = 0$ on the whole domain of variation \mathbb{C}^n of λ except of course possible isolated singularities.

The equations

An R -matrix solution of the DQYBE satisfying the zero weight condition takes the form: $R = \sum_{i,j=1}^n \Delta_{ij} e_{ij}^{(n)} \otimes e_{ji}^{(n)} + \sum_{i \neq j=1}^n d_{ij} e_{ii}^{(n)} \otimes e_{jj}^{(n)}$. The equations obeyed by its coefficients read:

$$\begin{aligned} \Delta_{ii}\Delta_{ii}(i)\{\Delta_{ii}(i) - \Delta_{ii}\} &= 0, & d_{ij}d_{ij}(i)\{\Delta_{ii}(j) - \Delta_{ii}\} &= 0, & d_{ij}\{\Delta_{ii}(j)\Delta_{ij}(i) - \Delta_{ii}(j)\Delta_{ij} - \Delta_{ji}\Delta_{ij}(i)\} &= 0, & d_{ji}d_{ji}(i)\{\Delta_{ii}(j) - \Delta_{ii}\} &= 0, & d_{ji}\{\Delta_{ii}(j)\Delta_{ij}(i) - \Delta_{ii}(j)\Delta_{ij} - \Delta_{ji}\Delta_{ij}(i)\} &= 0, \\ d_{ij}(i)\{\Delta_{ii}\Delta_{ji}(i) - \Delta_{ii}\Delta_{ji} + \Delta_{ji}\Delta_{ij}(i)\} &= 0, & \Delta_{ii}^2(j)\Delta_{ij} - (d_{ij}d_{ji})\Delta_{ij}(i) - \Delta_{ii}(j)\Delta_{ij}^2 &= 0, & d_{ji}(i)\{\Delta_{ii}\Delta_{ji}(i) - \Delta_{ii}\Delta_{ji} + \Delta_{ji}\Delta_{ij}(i)\} &= 0, & \Delta_{ii}^2\Delta_{ji}(i) - (d_{ij}d_{ji})(i)\Delta_{ij} - \Delta_{ii}\Delta_{ji}^2(i) &= 0, \\ \Delta_{ii}d_{ij}(i)d_{ji}(i) - \Delta_{ii}(j)d_{ij}d_{ji} + \Delta_{ij}(i)\Delta_{ji}\{\Delta_{ij}(i) - \Delta_{ji}\} &= 0, & d_{ij}(k)d_{jk}(i)d_{ik} - d_{ij}d_{jk}d_{ik}(j) &= 0, & d_{jk}d_{ik}(j)\{\Delta_{ij}(k) - \Delta_{ij}\} &= 0, & d_{ij}(k)\{\Delta_{ij}(k)\Delta_{jk} + \Delta_{ji}(k)\Delta_{ik} - \Delta_{ik}\Delta_{jk}\} &= 0, \\ d_{ij}(k)d_{ik}\{\Delta_{jk}(i) - \Delta_{jk}\} &= 0, & d_{jk}\{\Delta_{ij}(k)\Delta_{jk} + \Delta_{ik}(j)\Delta_{kj} - \Delta_{ij}(k)\Delta_{ik}(j)\} &= 0, & d_{ij}(k)d_{ji}(k)\Delta_{ik} - d_{jk}d_{kj}\Delta_{ik}(j) + \Delta_{ij}(k)\Delta_{jk}\{\Delta_{ij}(k) - \Delta_{jk}\} &= 0, \end{aligned}$$

Two equivalence relations yielding the classification

Consistency conditions on the cancelation of d -coefficients and Δ -coefficients lead to relevant partitions and ordering of the indices.

\mathcal{D} -relation: The relation defined by $i\mathcal{D}j \Leftrightarrow d_{ij} = 0$ is an equivalence relation ($\bar{i} = \mathbb{I}(i)$).

The propagation of the vanishing of Δ -coefficients follows key properties:

- If $\Delta_{ij} = 0$, then, $\Delta_{ik}\Delta_{kj} = 0$, for any $k \in \mathbb{N}_n^*$.
- If there exist $k \in \mathbb{N}_n^*$ such that $\Delta_{ik}\Delta_{kj} \neq 0$, then $\Delta_{ij} \neq 0$.

Δ -relation: The relation defined by $i\Delta j \Leftrightarrow \Delta_{ij}\Delta_{ji} \neq 0$ is an equivalence relation.

This defines a partition of $\mathbb{N}_n^* = \bigcup_{p=1}^r \mathbb{J}_p$ into Δ -classes.

Any \mathcal{D} -class \subset one single Δ -class \Rightarrow partition of any Δ -class $\mathbb{J}_p = \bigcup_{l=0}^{l_p} \mathbb{I}_l^{(p)}$ in \mathcal{D} -classes.

The vanishing of Δ -coefficients is a Δ -class property: For \mathbb{I}, \mathbb{J} two distinct Δ -classes, either $\Delta_{ij} = 0$ for all $(i, j) \in \mathbb{I} \times \mathbb{J}$, or all $\Delta_{ij} \neq 0$. One thus write $\Delta_{\mathbb{I}\mathbb{J}} = 0$ or $\Delta_{\mathbb{I}\mathbb{J}} \neq 0$. This leads to introduce a reduced Δ -incidence matrix $M^R \in \mathcal{M}_r(\{0, 1\})$, defined by its coefficients $M_{\mathbb{I}\mathbb{J}}^R = 1 \Leftrightarrow \Delta_{\mathbb{I}\mathbb{J}} \neq 0$ and $M_{\mathbb{I}\mathbb{J}}^R = 0 \Leftrightarrow \Delta_{\mathbb{I}\mathbb{J}} = 0$.

After partitioning and reordering the indices of Δ -classes, the reduced Δ -incidence matrix M^R is similar to a block diagonal matrix, each diagonal block being upper-triangular (with only 1's in the upper-triangular corner).

This block diagonal decomposition defines a partition of the set \mathbb{N}_n^* of Δ -classes in s subsets \mathbb{P}_q with $q \in \mathbb{N}_s^*$, and an associated partition of $\mathbb{N}_n^* = \bigcup_{q=1}^s \mathbb{K}_q$ with $\mathbb{K}_q = \bigcup_{p \in \mathbb{P}_q} \mathbb{J}_p$.

General solution and structure of the set of solutions

Any solution with at least two diagonal blocks in its reduced Δ -incidence matrix M^R , is reducible by some gauge to a decoupled R -matrix (each sub- R -matrix being a solution in a lower dimension) \Rightarrow we will only consider one \mathbb{K}_q block.

To solve the equations and express the solutions let us introduce the functions “sum”

$$S_{ij} = \Delta_{ij} + \Delta_{ji} \text{ and “determinant” } \Sigma_{ij} = \begin{vmatrix} d_{ij} & \Delta_{ij} \\ \Delta_{ji} & d_{ji} \end{vmatrix} \neq 0 \text{ (since } R \text{ is invertible).}$$

There is two constants S_q and $\Sigma_q (\neq 0)$ and a family of signs $(\epsilon_{\mathbb{I}})_{\mathbb{I} \in \{\mathbb{I}(i), i \in \mathbb{K}_q\}}$ such that:

Inside a \mathcal{D} -class, $\forall j, j' \in \mathbb{I}(i)$, $\Delta_{jj'} = \Delta_{\mathbb{I}(i)} = (S_q + \epsilon_{\mathbb{I}(i)} D_q)/2$, with $D_q = \sqrt{S_q^2 + 4\Sigma_q}$. For indices of distinct \mathcal{D} -classes $S_{ij} = S_q$ and $\Sigma_{ij} = \Sigma_q$, $\forall (i, j) \in \mathbb{K}_q^{(2, \mathcal{P})}$.

For indices of distinct \mathcal{D} -classes and of the same Δ -class \mathbb{J} , there is a family of constants:

$(f_{\mathbb{I}})_{\mathbb{I} \in \{\mathbb{I}(i), i \in \mathbb{J}\}} \neq 0$ such that:

$$\Delta_{ij}((\lambda_k)_{k \in \mathbb{I}(i) \cup \mathbb{I}(j)}) = \Delta_{\mathbb{I}(i)\mathbb{I}(j)}(\Lambda_{\mathbb{I}(i)}, \Lambda_{\mathbb{I}(j)}) = \frac{S_q}{1 - e^{A_q(\epsilon_{\mathbb{I}(i)}\Lambda_{\mathbb{I}(i)} - \epsilon_{\mathbb{I}(j)}\Lambda_{\mathbb{I}(j)})f_{\mathbb{I}(i)}}} \text{ and}$$

$$d_{ij}d_{ji} = (B_q - \Delta_{\mathbb{I}(i)\mathbb{I}(j)})(B_q - \Delta_{\mathbb{I}(j)\mathbb{I}(i)}), \quad \forall (i, j) \in \mathbb{J}^{(2, \mathcal{P})} \text{ with } e^{A_q} = \frac{D_q - S_q}{D_q + S_q},$$

$$B_q = \frac{D_q + S_q}{2} = \frac{S_q}{1 - e^{A_q}} \text{ and } \Lambda_{\mathbb{I}(i)} = \sum_{k \in \mathbb{I}(i)} \lambda_k \text{ (in the trigonometric case } S_q \neq 0).$$

The limit S_q going to 0 yields a rational type of solutions.

For indices of distinct Δ -class \mathbb{J}_p and $\mathbb{J}_{p'}$:

$$\Delta_{ij} = S_q = \Delta_{\mathbb{I}(i)\mathbb{I}(j)} \text{ (thus } S_q \neq 0), \quad \Delta_{ji} = 0 \text{ and } d_{ij}d_{ji} = \Sigma_q, \quad \forall (i, j) \in \mathbb{J}_p \times \mathbb{J}_{p'}.$$